

# JS-AUP28-1

## PRODUCT SPECIFICATION

### Data Sheet



# Contents

|                                                   |          |
|---------------------------------------------------|----------|
| <b>Change History of Revision .....</b>           | <b>3</b> |
| <b>1 Functional description .....</b>             | <b>4</b> |
| 1.1 Overview .....                                | 4        |
| 1.2 Product Features .....                        | 4        |
| 1.3 Performance .....                             | 5        |
| 1.4 Block Diagram .....                           | 6        |
| 1.5 Protocols .....                               | 6        |
| 1.6 Antenna .....                                 | 6        |
| 1.7 Product Application .....                     | 6        |
| <b>2 Pin definitions .....</b>                    | <b>7</b> |
| 2.1 Definition of Pin Assignment .....            | 7        |
| 2.2 Description of geomagnetic sensors .....      | 7        |
| <b>3 Electrical Specifications .....</b>          | <b>8</b> |
| <b>4 Mechanical Specifications .....</b>          | <b>8</b> |
| <b>5 Version of the configuration .....</b>       | <b>9</b> |
| <b>6 Interface configuration selections .....</b> | <b>9</b> |
| 6.1 Interfaces description .....                  | 9        |
| <b>7 ROHS .....</b>                               | <b>9</b> |

## Change History of Revision

| Revision | Date       | Contents of Revision Change  | Remark   |
|----------|------------|------------------------------|----------|
| V1.0     | 2022-01-08 | First release                | Wang Wei |
| V1.1     | 2022-03-31 | Adding configuration options | Wang Wei |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |
|          |            |                              |          |

# 1 Functional description

## 1.1 Overview

The JS-AUP28-1 uses multi mode solution, low power consumption, low cost, the JS-AUP28-1 are multi GNSS (BDSGPS,,GLONASS,Galileo,QZSS and SBAS) positioning module developed to meet the requirements of an extensive range of applications and end-products. Based on the high performance SOC position engine, these receivers provide exceptional sensitivity and acquisition times and interference suppression measures enable reliable positioning even in difficult signal conditions.

## 1.2 Product Features

- SOC high performance GNSS Chips
- Over 2 million effective correlators
- 72 acquisition-channel / 32 tracking
- Cold start acquisition sensitivity of -148dBm and -166dBm tracking sensitivity
- Up to 10 Hz navigation update rate
- Supports BDS,GPS, QZSS, SBAS,GLONASS ,Galileo
- Supports AGPS
- Integrated TCXO, LNA, SAW, RTC
- Compact size (28.0mmx28.0mmx8.6mm±0.3mm) suitable for space-sensitive application
- Support standard NMEA 0183, version 4.0 and 4.1, UBX

### 1.3 Performance

| Parameter                                 | Specification                                                                                                                                                            |  |
|-------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| Receiver type*                            | <div> <div>■GPS/QZSS L1C/A</div> <div>■SBAS EGNOS, GAGAN, MSAS and WAAS</div> </div> <div> <div>■GLONASS L1OF</div> <div>■BDS B1I</div> <div>■Galileo E1B/C</div> </div> |  |
| Sensitivity                               | <div>Tracking &amp; Navigation -166dBm</div> <div>Reacquisition -160dBm</div> <div>Cold Start -148dBm</div>                                                              |  |
| Time-To-First-Fix <sup>1</sup>            | <div>Cold Start 29s</div> <div>Hot Start 1s</div>                                                                                                                        |  |
| Horizontal Position accuracy <sup>2</sup> | Autonomous 2.0m CEP                                                                                                                                                      |  |
| Accuracy of time pulse signal             | <div>RMS 30ns</div> <div>99% 60ns</div>                                                                                                                                  |  |
| Velocity accuracy <sup>3</sup>            | 0.05m/s                                                                                                                                                                  |  |
| Operational limits <sup>4</sup>           | <div>Dynamics ≤ 4g</div> <div>Altitude 80000m</div> <div>Velocity 500m/s</div>                                                                                           |  |
| Frequency of time pulse signal            | 1Hz                                                                                                                                                                      |  |
| Baud Rate                                 | 9,600 -- 460800 bps (Default 38400 bps)                                                                                                                                  |  |
| Max navigation update rate                | 10 Hz (Default 1Hz, configurable)                                                                                                                                        |  |

\*Default GPS+Galileo+QZSS+SBAS, and BDS and GLONASS are not supported at the same time

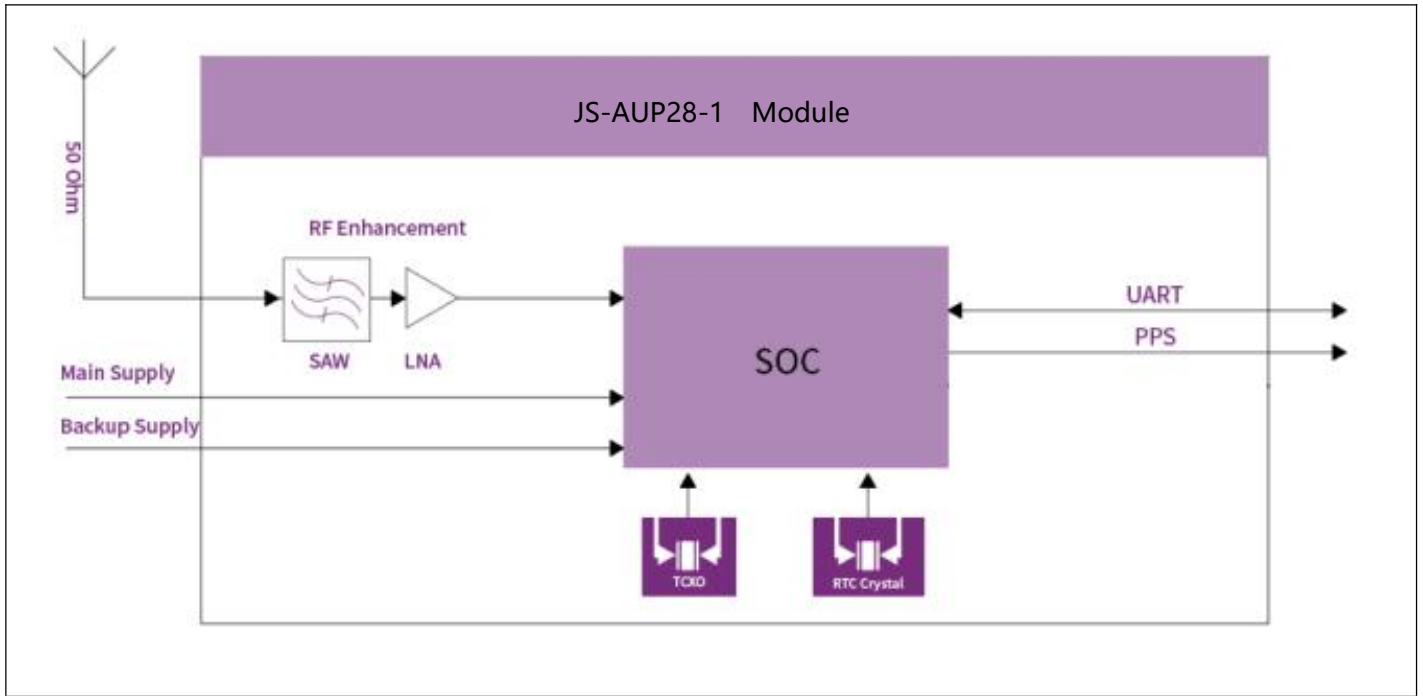
<sup>1</sup> All satellites at ≥-130dBm

<sup>2</sup> CEP 50%, 24 hours static, ≥-130dBm, > 6SVs

<sup>3</sup> 50% at 30 m/s for dynamic operation

<sup>4</sup> Assuming Airborne < 4g platform

## 1.4 Block Diagram



## 1.5 Protocols

| Protocol               | Type                                     |
|------------------------|------------------------------------------|
| NMEA 0183 v4.0 and 4.1 | Input/output, ASCII                      |
| UBX                    | Input/output, binary, u-blox proprietary |

## 1.6 Antenna

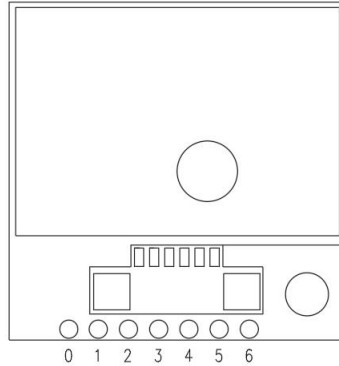
| Parameter            | Specification   |
|----------------------|-----------------|
| Passive Antenna Type | 25.0*25.0*4.0mm |

## 1.7 Product Application

- UAV
- Automotive application
- Marine navigation, fleet management
- Handheld GPS receiver application
- Intelligent logistics scheduling
- Personnel protective
- Car navigation and tracking
- Intelligent robot

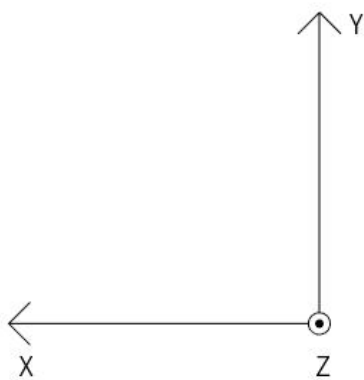
## 2 Pin definitions

### 2.1 Definition of Pin Assignment

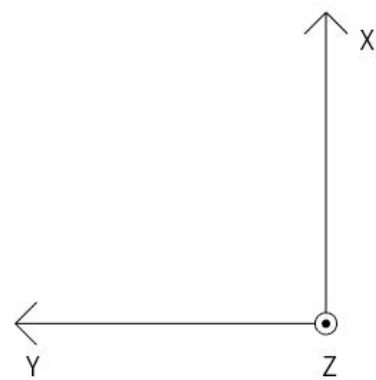


| No. | Name     | I/O | Description                    |
|-----|----------|-----|--------------------------------|
| 0   | 1PPS     | O   | 1PPS                           |
| 1   | GND/SCL  | G   | Ground/I2C Clock               |
| 2   | GND      | G   | Ground                         |
| 3   | TX       | O   | TTL Output                     |
| 4   | RX       | I   | TTL Input                      |
| 5   | VCC      | P   | Main Supply                    |
| 6   | VBAT/SDA | P   | Backup voltage supply/I2C Data |

### 2.2 Description of geomagnetic sensors



IST8310  
Magnetic compass direction



VCM5883(Default)  
Magnetic compass direction

Note: Magnetic compass model: The geomagnetic model is VCM5883(Default) , VCM5883\_MS\_ADDRESS 0x0C. The geomagnetic model is IST8310 , IST8310\_MS\_ADDRESS 0x0F.

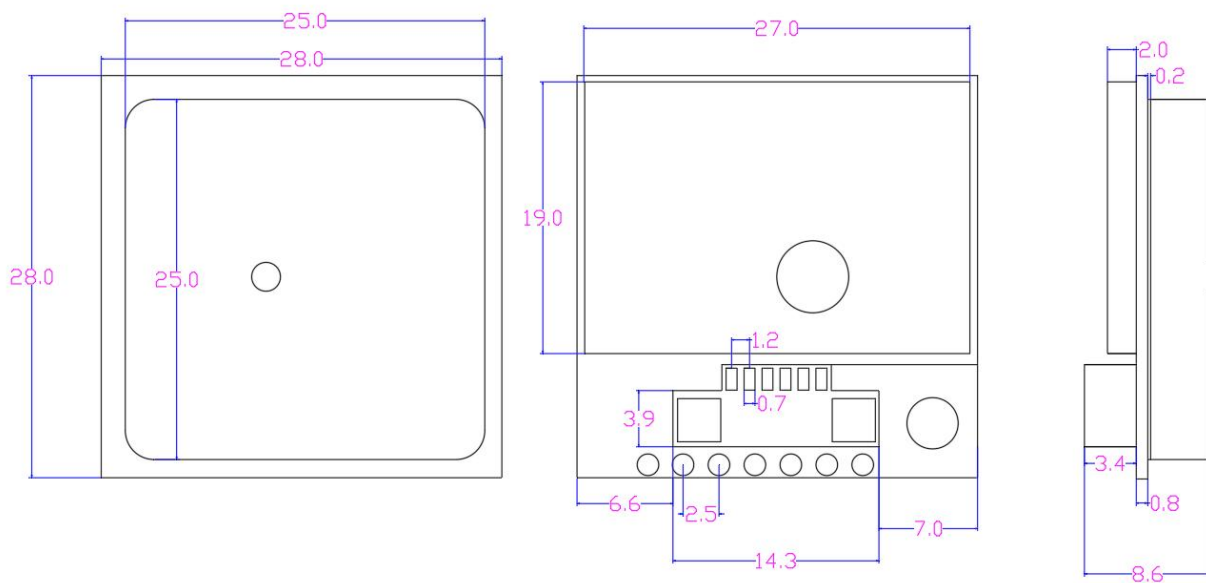
### 3 Electrical Specifications

| Parameter                          | Symbol      | Min     | Type    | Max     | Units |
|------------------------------------|-------------|---------|---------|---------|-------|
| Power supply voltage               | VCC         | 3.3     | 5.0     | 5.5     | V     |
| Average supply current             | Acquisition | 27@5.0V | 35@5.0V | 41@5.0V | mA    |
|                                    | Tracking    | 27@5.0V | 32@5.0V | 40@5.0V | mA    |
| Backup battery                     |             |         | 0.07    |         | F     |
| Backup battery current             | I_BCKP      |         | 8@3.3V  |         | uA    |
| Digital IO voltage                 | Div         | 3.3     |         | 3.3     | V     |
| Storage temperature                | Tstg        | -40     |         | 85      | °C    |
| Operating temperature <sup>1</sup> | Topr        | -40     |         | 85      | °C    |
| Farah capacitance <sup>2</sup>     | Tstg        | -25     |         | 60      | °C    |
| Humidity                           |             |         |         | 95      | %     |

<sup>1</sup> The temperature range is the operating temperature range without the Farad capacitor

<sup>2</sup> Hot start cannot be carried out when the temperature is below -20°C or above 60°C

### 4 Mechanical Specifications



units: mm      dimension error:±0.3mm

## 5 Version of the configuration

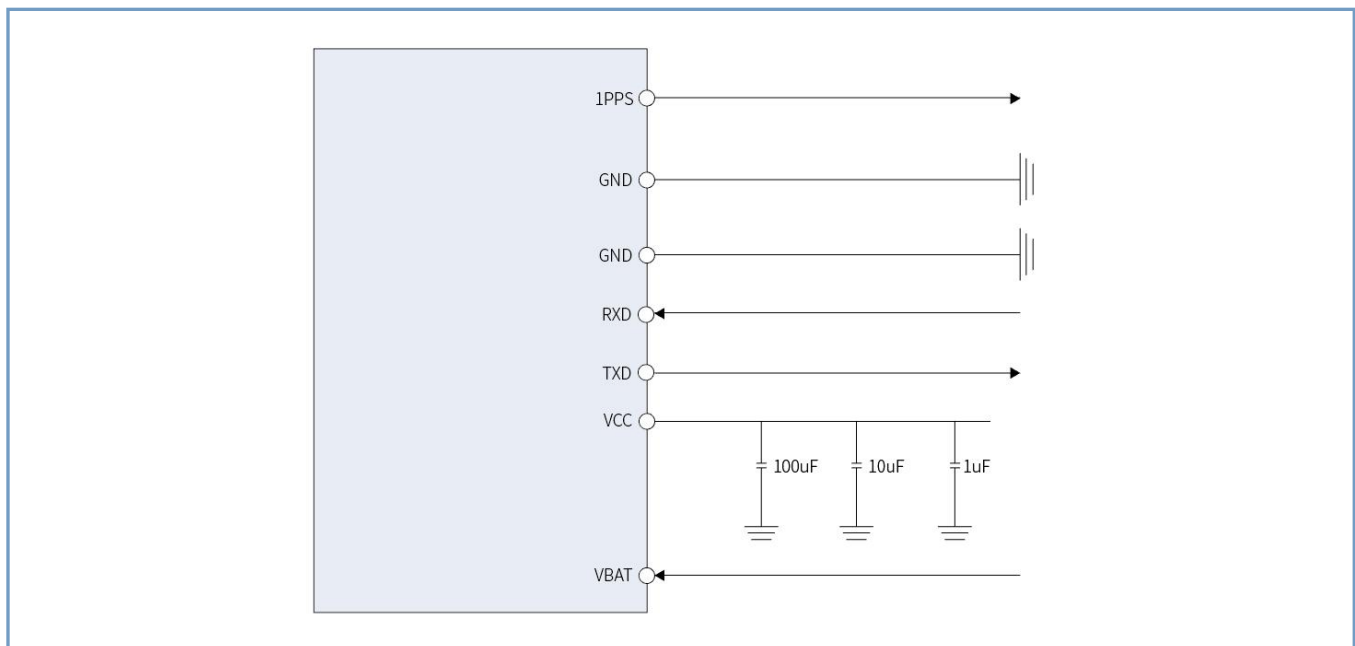
| NAME         | TTL | FLASH | IST8310/VCM5883 | Farah capacitance |
|--------------|-----|-------|-----------------|-------------------|
| JS-AUP28-1   | √   | NC    | NC              | √                 |
| JS-AUP28GF-1 | √   | √     | √ ( I2C )       | √                 |
| JS-AUP28F-1  | √   | √     | NC              | √                 |
| JS-AUP28NF-1 | √   | √     | NC              | NC                |

## 6 Interface configuration selections

### 6.1 Interfaces description

The JS-AUP28-1 GPS module can be selected according to the needs of the corresponding interface output side and additional sensors, Support UART interface output

### Application Circuit



## 7 ROHS

This product is RoHS compliance